

ImagingLab Robotics Library for DENSO

Release Notes

Improvements and Corrections

Version	First Release	Last Update	Description
2.2.15	2009-11-24	2009-12-02	Removed dependency on LabVIEW Real-Time Module (NI_Real-Time Libraries.lvlib) during development on Windows OS targets.
		2009-12-02	Fixed dependency conflicts for "dir.mnu" palette set files.
		2009-12-02	Added four new examples and revised example structure.
2.2.16	2010-01-26	2010-01-26	Improved performances in terms of execution speed and memory allocation of low level VIs.
2.2.17	2010-07-20	2010-07-20	Fixed bug in pass motion selection on "DRL_Drive.vi".
		2010-07-20	Added the new folder "HelpFiles" into the library directory structure.
3.0.4	2010-10-26	2010-10-26	Modified licensing scheme.
3.0.7	2011-02-17	2011-02-17	Fixed licensing scheme.
3.0.8	2011-03-08	2011-03-08	Reviewed VI icons.
		2011-03-08	Reviewed library installer.
		2011-03-08	Removed evaluation popup message.
3.0.9	2011-03-17	2011-03-17	Fixed licensing for LabVIEW 2010.
3.0.10	2011-04-13	2011-04-13	Fixed licensing scheme.
3.0.11	2011-06-09	2011-06-09	Fixed licensing scheme.
3.0.12	2011-06-17	2011-06-17	Fixed licensing scheme.
3.0.13	2011-09-02	2011-09-02	Fixed licensing for LabVIEW 2011.
3.0.14	2011-11-22	2011-11-22	Reviewed license file check.
3.1.0	2012-01-31	2012-01-31	Refreshing: icons, examples, front panels, help. Palette moved from the user.lib to the vi.lib folder. Examples integrated into NI Example Finder.

Examples

Use the NI Example Finder (Help»Find Examples) to find and launch ImagingLab Robotics Library for Denso examples.

*Please use the following keywords: **robot, robots, robotics, Denso.***

